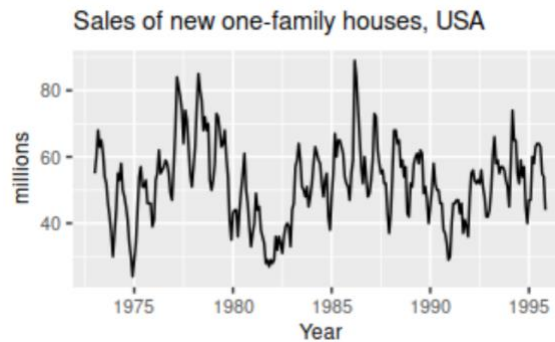
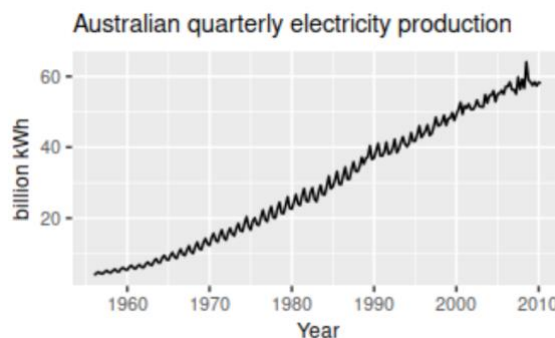


# Forecasting Trends and Seasonality

- General features of time series can be classified within three categories
  - Trends
  - Seasonality
  - Cycles
- A time series usually exhibits two or more of these features
  - E.g. seasonal and cyclical



- E.g. seasonal and trending



## Trends

- Trend – a smooth, typically unidirectional pattern in the data that arises from the accumulation of information over time
  - i.e. a long-term increase or decrease in the data
  - Doesn't have to be linear
- ACF of trended series tend to have positive values that slowly decrease as the lags increase
  - i.e. When the data is trending ACF for small lags tend to be large and positive
  - This is because observations nearby are also nearby in size

## **Trend Models**

- Trend models are (relatively) easy to fit and forecast
- 4 types
  - Linear –  $y_t = \alpha + \beta t$ 
    - Simplest model that can be used to account for a trending time series

- Polynomial –  $y_t = \alpha + \beta_1 t + \beta_2 t^2 + \dots + \beta_p t^p$ 
  - E.g. quadratic, cubic, etc.
  - Caution is needed with (higher order) ones, as they may fit well in-sample, but this does not translate to good performance for out-of-sample
  - In fact, it is basically guaranteed that as you introduce more and more higher order polynomials, the out-of-sample forecast will deteriorate considerably
- Exponential –  $y_t = e^{\alpha + \beta t}$  OR  $\ln(y_t) = \alpha + \beta t$ 
  - Suitable when a time series is characterised with a stable relative/percentage change over time (e.g. GDP)
- Shifting (or switching) –  $y_t = \alpha + \beta_1 t + \beta_2(t - \tau)I(t > \tau)$ ,  $\tau \in T$ 
  - Within some range, there is a linear trend but then at some point there is a shift and we end up getting a different trend
- Exponential trend is same as a linear trend fitted to natural logarithm of the series
  - For a time series  $\{y_t: t = 1, \dots, T\}$ , the natural log is  $z_t = \ln(y_t)$
  - Transforming the model is beneficial as the transformed model
    - Is easier to interpret (can identify relative/percentage change)
    - Homogenizes the variance of the time series
    - May result in improved forecasting accuracy
  - Fitted trend can be reverse-transformed to fit the original series –  $\hat{y}_t = e^{\hat{z}_t}$

### Fitting and Forecasting Trends

- Generic representation of a trend model with an additive error term –  $y_t = g(t; \theta) + \varepsilon_t$ 
  - Estimate  $\theta$  by fitting the trend model to a time series using the least-squares regression –  $\hat{\theta} = \operatorname{argmin}_{\theta} \sum_{t=1}^T (y_t - g(t; \theta))^2$
  - Fitted values are given by –  $\hat{y}_t = g(t; \hat{\theta})$
- Any future *realization* of a random variable assumed to follow a linear trend model is  $y_{t+h} = \alpha + \beta(t+h) + \varepsilon_{t+h}$ 
  - $t+h$  is the trend variable
- Optimal *forecast* –  $y_{t+h|t} = E(y_{t+h} | \Omega_t) = E[\alpha + \beta(t+h) + \varepsilon_{t+h}] = \alpha + \beta(t+h)$ 
  - i.e.  $E(y_t) = \alpha + \beta t$  – doesn't satisfy stationarity condition
  - Forecast error –  $e_{t+h|t} = y_{t+h} - y_{t+h|t} = \varepsilon_{t+h}$ 
    - This implies that the forecast error from this model will have exactly the same characteristics as what we assume about  $\varepsilon$  (white noise)
  - Forecast variance –  $\sigma_{t+h|t}^2 = E(e_{t+h|t}^2) = E(\varepsilon_{t+h}^2) = \sigma^2, \quad \forall h$ 
    - i.e.  $\operatorname{Var}(y_t) = \sigma^2$  – variance is time-invariant
    - Assumes forecast variance doesn't change with the horizon, which is perhaps an incorrect assumption

- Density forecast –  $f(Y_{t+h}|t|\Omega_t) \rightarrow N(\alpha + \beta(t + h), \sigma^2)$
- Features of trend forecasts
  - Tend to understate uncertainty at long horizons
  - Short-term trend forecasts *can* perform poorly, while long-term trend forecasts *typically* perform poorly
  - Sometimes it may be beneficial to forecast growth rates and reconstruct level forecasts from growth