

HYDRAULICS

Date _____ No _____

Chpt 1

1. Def

Fluid: A substance that deforms continuously

under a shear force

(in liquid or gas phase)

Shear stress applied to solid

→ deform or bend to a certain level

liq gas

not easily compressed can be compressed

occupy fixed volume fill entire volume

2. Unit

BA sys:

① length: foot (ft) ② time: s

③ mass: slug ④ force: pound (lb)

⑤ temperature: Fahrenheit (°F) or

absolute temp in Rankine (°R)

$^{\circ}R = ^{\circ}F + 459.67$

$^{\circ}C = (^{\circ}F - 32) \frac{5}{9}$

EE sys:

① length: foot (ft) ② time: s

③ temp: abs temp in Rankine (°R)

④ mass: pound mass (lbm)

⑤ pound (lb)

Date _____ No _____

Chpt 2

Fluid Concepts

1. Continuum assumptions
 - Valid if the mean free path of the molecules is (10^{-9} m for gases) much less than the smallest significant dimension of the problem ($< 10^{-6}$ m)

• both air & water satisfy under normal condition

— under continuum assumption:
 fluid properties are continuous functions of time; e.g. $\rho = \rho(x, y, z, t)$

2. measures of fluid mass & weight

- 1) ave density: $\rho = m/v$
- 2) specific volume: $v = 1/\rho$
- 3) specific weight: $\gamma = \rho g$

4) specific gravity SG: non-dim

$$SG = \rho / \rho_{H_2O at 4^\circ C}$$

At $0^\circ C$
 substance
 water
 mercury 13.6

fluid: ρ depends slightly on T & P under normal conditions.

gases: depend significantly on T, P

3. Ideal gas law!

— hypothetical gas consisting of identical particles of zero volume, with no intermolecular forces, elastic collisions with wall

$$\text{law: } P = \rho R T$$

P: abs pressure $P = p + p_0$
 p_0 : gauge pressure

$T = {}^\circ C + 273.15 \text{ (K)}$
 R: gas constant (air is $R = 286.9 \text{ J/(kg}\cdot\text{K)}$)
 (depending on gas type & related to molecule weight)

4. Velocity field

1) velocity at a point: the instant velocity of the fluid particle passing through the point

$$\vec{V} = \vec{V}(x, y, z, t) \quad \leftarrow \begin{matrix} \text{with } t: \text{unsteady} \\ \text{without } t: \text{steady} \end{matrix}$$

5. Types

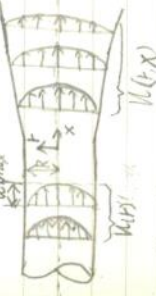
1) dependence on time of props

$$\text{steady: } \frac{\partial \eta}{\partial t} = 0 \quad (\eta \text{ flow prop})$$

2) unsteady: $\frac{\partial \eta}{\partial t} \neq 0$

1, 2, 3 - dim flow

Uniform flow at cross section:
 velocity const at cross-section



$$u = u_{max} \left[1 - \left(\frac{r}{R} \right)^2 \right]$$

3) velocity const or not
 const $\vec{V} \rightarrow$ uniform flow
 non $\vec{V} \rightarrow$ non-

6. Flow visualisation methods

- 1) path lines
- 2) streakline:
 - a line joining particles passing through a fixed location in space
- 3) streamlines
 - line joining particles passing through a fixed location in space
- 4) timelines:
 - a set of adjacent fluid particles that were marked at the instant in time.

Exmp: velocity field given by $\vec{v} = 0.3x^2 - 0.3y^2$

1) velocity of particle at (2,8)

2) equation of streamlines

3) plot streamlines

4) if the particle passing through (2,8) is marked at $t=0$, determine location of it at $t=6s$

5) show the equation of the particle path is the same as equation of stream line

6) $\vec{v} \cdot \nabla = 0$

7) $\vec{v} \cdot \nabla = 0$

8) $\vec{v} \cdot \nabla = 0$

9) $\vec{v} \cdot \nabla = 0$

10) $\vec{v} \cdot \nabla = 0$

11) $\vec{v} \cdot \nabla = 0$

12) $\vec{v} \cdot \nabla = 0$

13) $\vec{v} \cdot \nabla = 0$

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28) $\vec{v} \cdot \nabla = 0$

29) $\vec{v} \cdot \nabla = 0$

30) $\vec{v} \cdot \nabla = 0$

7. Stress field

1) type of forces on fluid particles:

2) body forces

3) surface forces

4) normal stress

5) shear stress

6) normal stress

7) shear stress

8) normal stress

9) shear stress

10) normal stress

11) shear stress

12) normal stress

13) shear stress

14) normal stress

15) shear stress

16) normal stress

17) shear stress

18) normal stress

19) shear stress

20) normal stress

21) shear stress

22) normal stress

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32) normal stress

33) shear stress

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35) shear stress

36) normal stress

37) shear stress

38) normal stress

39) shear stress

40) normal stress

41) shear stress

42) normal stress

43) shear stress

44) normal stress

45) shear stress

46) normal stress

47) shear stress

48) normal stress

8. Viscosity

(internal friction) measure of fluid's resistance to flow

1) Newton's law of viscosity

2) shear stress

3) shear rate

4) shear stress

5) shear rate

6) shear stress

7) shear rate

8) shear stress

9) shear rate

10) shear stress

11) shear rate

12) shear stress

13) shear rate

14) shear stress

15) shear rate

16) shear stress

17) shear rate

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37) shear rate

38) shear stress

39) shear rate

40) shear stress

41) shear rate

42) shear stress

43) shear rate

44) shear stress

45) shear rate

46) shear stress

47) shear rate

Q2-2: 9 type of fluids
exp following using F-L-T
a) P b) Pressure
c) power d) energy
e) mass flux
f) Volume flow rate

- most of common fluids: e.g. water, air, gasoline
a) $\rho = F T^2 / L^3$
b) $P_{int} = F / L^2$ 2) Non-Newtonian fluids
- shear stress not proportional to deformation rate
c) $P_{int} = F / L^2$
d) $\dot{\epsilon} = F / L$
e) $\dot{\epsilon} = F T^2 / L^3$
f) $V_{flow} = L^3 / T$
- bingham fluids, shear thinning and shear thickening fluids...

10. Surface tension
1) develops at interfaces with other liquids
of solids due to the attraction between molecules

2) Surface tension: force/length (N/m)
3) interface acts like a stretched elastic membrane (with a contact angle θ)

4) θ and σ depend on the type of liquid and contact surface
creating surface tension σ



Example: Non-Newtonian fluid: 008 lck
= 0.08 lck water
(shear thickening fluid)
as $\tau \uparrow, \dot{\epsilon} \uparrow$
Painting is the opposite
(shear thinning fluid)
as $\tau \uparrow, \dot{\epsilon} \downarrow$

10.1 Pressure inside a drop of fluid
O: surface tension (N/m)
 $\Delta p = p_i - p_e$
(p_i : internal pressure, p_e : external pressure)
force around the edge: $2\pi R \sigma$
force due to pressure difference: $\Delta p \pi R^2$
balance: $2\pi R \sigma = \Delta p \pi R^2$
 $\Rightarrow \Delta p = \frac{2\sigma}{R}$



* pressure in flow
a) Law of hydrostatic pressure (no motion)
(still applies if fluid in motion only in horizontal)
b) pipe flow
(typically, horizontal change $\gg$ vertical pressure change)

10.2 Eq application
- insignificant for large scale of motions
- important for some small scale motions:
e.g. capillary rise (or depression)



Wet surface
Non wetting surface
A: neglect vertical variation in pressure + assume uniform across the cross-section
B: Free jets
fluid jets open to atm all sides
e.g. garden hose
- $p = p_{atm}$ everywhere in free jet

1) Compressibility of fluids
is incompressible fluids
- density change negligible: $\frac{dp}{dt} = 0$
- liquids & gases with small Mach number
 $M = \frac{V}{c} < 0.3$, c : speed of sound
 V : flow velocity

2) compressible fluids

- density change not negligible
- e.g. flow of gases (M 0.3); some flow of liquids under extremely high pressure (water hammer)

12. Bulk modulus

- Bulk compressibility modulus (or modulus elasticity)
- ratio of pressure change to relative density change (compressibility)
- Unit: N/m^2 , Pascal
- $E_v = \frac{dp}{\frac{d\rho}{\rho}}$

13. compression & expansion of gases

- when gases compressed (expanded), relationship between pressure and density depends on the nature of the process
- 1) under constant temperature condition (T-):
 $\frac{p}{\rho} = \text{const}, E_v = p$

- 2) under isentropic conditions (frictionless compression and no heat exchange with surroundings)
 $\frac{p}{\rho^k} = \text{const}, E_v = kp$

k : ratio of the specific heat at const pressure, c_p , to the specific heat at const volume c_v ($R = c_p - c_v$)
(Note: pressures are abs pressures)

14. speed of sound

- 1) disturbances in fluids travel at speed of sound.
- 2) speed of sound in fluids:

$$c = \sqrt{\frac{dp}{d\rho}} = \sqrt{\frac{E_v}{\rho}}$$

- 3) for gases undergoing isentropic process $E_v = kp$

$$c = \sqrt{k p / \rho}$$

$$c_{\text{ideal gas}}: c = \sqrt{k R T}$$

15. Vapour pressure

- a pressure developed in a vacuum space left above the liquid in a closed container
- T ↑, p_v ↑
- boiling: when the absolute pressure reaches p_v for fluid passing valve and pumps
- importance in engineering appli:
When $p < p_v \Rightarrow$ Vapour bubble (low p)
 $\Rightarrow$ swept along high p $\Rightarrow$ bubble collapse
 $\Rightarrow$ may damage the structures
— Cavitation



16. Classification of fluid motions

16.1 viscous and inviscid flows

- all real fluids are viscous
- flows assumed inviscid when viscosity not important
- total drag on an airfoil
- analysis of inviscid flows much simpler than viscous
- Laplace equation (for irrotational flows)
- Navier-Stokes equations (for viscous flows)



16.2 laminar & turbulent flows

- laminar flow
 - fluid particles move in smooth layers
- turbulent flow
 - fluid particles mix rapidly with random three-dimensional velocity fluctuations.

$$\vec{v} = u\hat{i} + v\hat{j} + w\hat{k}$$

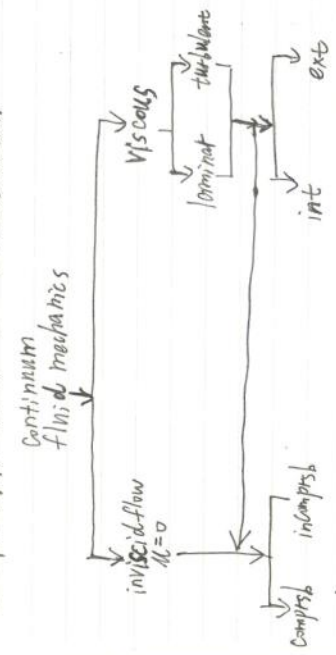
laminar → turbulent

16.3 Internal & external flows

- internal flows
 - flows completely bounded by solid surfaces. (e.g. flow in pipes)
- external flows
 - flows over bodies immersed in unbounded fluid (e.g. flow around a submarine)

both int & ext flows may be laminar/turbulent
compressible/incompressible

Classification of fluid motion



chpt 3 Hydrostatics

Fluid statics { no relative motion between fluid particles (why?)
no shear stress ($\tau = \mu \frac{du}{dy} = 0$)
normal stress (pressure) exists

1. Pascal's law
on arbitrary wedge-shaped element!



Newton's 2nd law

$$\sum F_y = m a_y; P_g \delta x \delta z - P_s \delta x \delta y \sin \theta = \rho \delta x \delta y \delta z a_y$$

$$\sum F_z = m a_z; P_z \delta x \delta y - \gamma \frac{\delta x \delta y \delta z}{2} - P_s \delta x \delta y \cos \theta = \rho \delta x \delta y \delta z a_z$$

Since $\delta y = \delta z \cos \theta$; $\delta z = \frac{\delta y}{\cos \theta}$

$$\Rightarrow P_g - P_s = \rho a_y \frac{\delta y}{2}$$

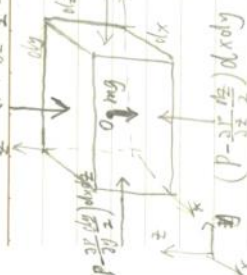
$$P_z - P_s = (\rho a_z + \gamma) \frac{\delta z}{2}$$

$$\text{When } \delta y \rightarrow 0 \text{ and } \delta z \rightarrow 0 \Rightarrow P_s = P_y = P_z$$

$\Rightarrow$ Pressure at a point is independent of direction (Pascal's law) - a scalar property of fluid.

2. Pressure variation in a static fluid.
1) body force 2) surface forces.

$$(P + \frac{\partial P}{\partial z} \frac{\delta z}{2}) \delta x \delta y$$



Total forces:

$$X: \sum F_x = -\frac{\partial P}{\partial x} \delta x \delta y \delta z$$

$$Y: \sum F_y = -\frac{\partial P}{\partial y} \delta x \delta y \delta z$$

$$Z: \sum F_z = -\frac{\partial P}{\partial z} \delta x \delta y \delta z - mg$$

Applying Newton's 2nd law

$$\sum F_x = m a_x \quad \text{since } m = \rho \delta x \delta y \delta z$$

$$\sum F_y = m a_y \quad \frac{\partial P}{\partial x} = -\rho a_x$$

$$\sum F_z = m a_z \quad \frac{\partial P}{\partial y} = -\rho a_y$$

$$\frac{\partial P}{\partial z} = -\rho (g + a_z)$$

Restrictions:

$$1) a_x = a_y = a_z = 0$$

$$2) \frac{\partial P}{\partial x} = 0$$

$$3) \frac{\partial P}{\partial y} = 0$$

$$\frac{\partial P}{\partial z} = -\rho g = -\gamma$$

$\Rightarrow$ P only depends on z

$$\Rightarrow \frac{dP}{dz} = -\rho g = -\gamma$$

2.1 Pressure change - Integral form:

for incompressible fluids, integrate $\frac{dP}{dz} = -\rho g = -\gamma$

$$\int dP = -\gamma \int dz \Rightarrow P = -\gamma z + \text{const}$$

$$\Rightarrow P + \gamma z = \text{const}$$

$$\text{or } \frac{P}{\gamma} + z = \text{const}$$

Piezometric head

At two points 1, 2 in liquid: Pressure head (m)

$$\frac{P_1}{\gamma} + z_1 = \frac{P_2}{\gamma} + z_2 \quad \text{or} \quad P_2 - P_1 = \gamma(z_1 - z_2) = \Delta P$$

Exmp: Oil $\gamma = 800 \text{ kg/m}^3$

At $z_1 = 0, P_1 = 0 \rightarrow \text{Const} = 0$
 $P_2/\gamma - h = 0 \Rightarrow P_2 = \gamma h = \rho g h$ (gauge)

2.2 Absolute pressure & gauge pressure

$$P_{abs} = P_{gauge} + P_{atm}$$

— pressure values must be stated with respect to a reference

2.3 pressure transmission throughout a stationary fluid

- pressure is a const on a line if
 - line horizontal
 - stationary fluid is uniform and
 - stationary fluid is continuous.

3. Measurement of pressure

- o pressure measurement devices:
 - manometry barometer: for atmospheric pressure.
 - manometers: for gage pressure using liquid columns.
 - inverted / inclined tubes.
 - mechanical & electronic pressure measuring devices.
- o in engineering, normally use gauge pressure. for abs pressure, P_{abs} must be indicated.

3.1 Mercury barometer — find P_{atm}

$$P_{atm} = \rho_{Hg} g h$$

Date No Page = $P - P_{atm}$

3.2 Piezometer tube — to find P_A for P_i

$$P_i = P_{atm} + \gamma_1 h_1 (\text{abs})$$

$$P_i = \gamma_1 h_1 (\text{gauge})$$



3.3 U-Tube manometer — P_A

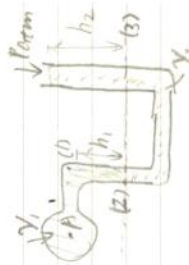
$$P_2 = P_3, \quad P_B = P_1$$

$$P_2 = P_1 + \gamma_1 h_1 = P_A + \gamma_1 h_1$$

$$P_3 = P_{atm} + \gamma_2 h_2$$

$$P_A = P_{atm} + \gamma_2 h_2 - \gamma_1 h_1 (\text{abs})$$

$$P_A = \gamma_2 h_2 - \gamma_1 h_1 (\text{gauge})$$



3.4 Differential U-tube manometer to find $P_A - P_B$

$$P_B = P_1, \quad P_1 + \gamma_1 h_1 = P_2$$

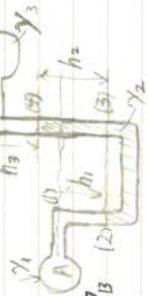
$$P_2 = P_3, \quad P_3 - \gamma_2 h_2 = P_4$$

$$P_4 - \gamma_3 h_3 = P_B$$

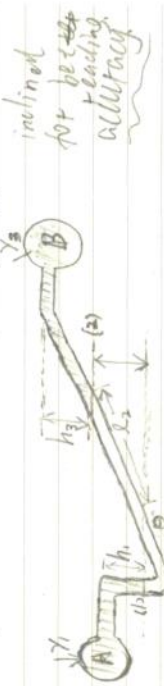
Adding up: $P_A + \gamma_1 h_1 - \gamma_2 h_2 - \gamma_3 h_3 = P_B$

Differential pressure:

$$P_A - P_B = \gamma_2 h_2 + \gamma_3 h_3 - \gamma_1 h_1$$



Inclined-tube manometer to find $P_A - P_B$



$$P_A + \gamma_1 h_1 - \gamma_2 L_2 \sin \theta - \gamma_3 h_3 = P_B$$

OR: $P_A - P_B = \gamma_2 L_2 \sin \theta + \gamma_3 h_3 - \gamma_1 h_1$

4. ~~Hydrostatic~~ Hydrostatic force on submerged surfaces
 o quantities of interests

- magnitude of force
- direction of force
- location of action of force
- o basic equation
- o $p = p_0 + \gamma h$ or $p = \gamma h$ with $\gamma = \rho g$
- o method - integration

4.1 Hydrostatic force on a flat surface

- o magnitude: $F = p_c \cdot A$, p_c is pressure at centroid
- o direction: perpendicular to surface
- o location of action or centre of pressure - to find



$$F = p_c A$$

$$F_R = \int_A p_c dA = \int_A \rho g h dA = \rho g \int_A h dA$$

$\int_A h dA = y_c A$ → first moment of area

$$F_R = \rho g y_c A = \gamma y_c A = p_c A \quad (\text{Force magnitude})$$

(p_c : gauge pressure at centroid of A)

$$F_{\text{total}} = \text{pressure at Centroid} \times \text{total area}$$

Location of resultant force - pressure centre
 moment of resultant force about x axis
 = moment due to distributed force about same axis

$$y' F_R = \int_A y p_c dA = \int_A y \gamma y dA$$

$$y' = \frac{\gamma \int_A y^2 dA}{F_R} = \frac{\gamma \int_A y^2 dA}{\gamma y_c A} = \frac{\int_A y^2 dA}{y_c A}$$

$\int_A y^2 dA = I_x$ ← Second moment of the area about x-axis
 with parallel axis theorem:

$$I_x = I_{xc} + A y_c^2$$

(I_{xc} : second moment of the area with respect to an axis passing through its centroid and parallel to x-axis)

$$\textcircled{1} + \textcircled{2} \Rightarrow y' = \frac{I_{xc}}{A y_c} + y_c \quad (\text{Force acting location})$$

Resultant does not pass through centroid as $I_{xc}/(y_c A) > 0$

$$\text{Similarly, } x' = \frac{I_{xy}}{y_c A} = x_c + \frac{I_{xc}}{y_c A}$$

where $I_{xy} = \int_A xy dA = I_{xyc} + A x_c y_c$
 is product of inertia with respect to x & y
 - direction of resultant force is perpendicular to the plane.

Exmps:

A: vertical wall, width b, height h
 Force on plate

$$F_R = p_c A = \gamma y_c A = (\gamma h/2)(bh) = \gamma b h^2/2$$

$$p_c = \gamma h/2 \text{ pressure at Centroid}$$

Pressure centre: $y_R = y_c + \frac{I_{xc}}{A y_c}$, $A = bh$, $\Rightarrow y_R = \frac{2h}{3}$

Exmp B:

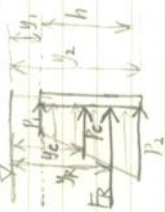
Force on the plate: $F_R = p_c A$
 Centroid: $y_c = (L \sin \theta) / 2$
 Pressure at Centroid:
 $p_c = \gamma y_c = \gamma (L \sin \theta) / 2$
 Area: $A = bL$
 $F_R = \gamma (L \sin \theta) / 2 \times bL = (\gamma b L^2 \sin \theta) / 2$



Pressure center $y_R = y_c + \frac{I_{xc}}{A y_c}$ with $y_c' = L/2$
 with $I_{xc} = \frac{1}{12} b L^3$, $A = bL$
 $\Rightarrow$ Pressure Center $y_R' = 2L/3$

Exmp C: submerged vertical wall, width b, height h

Force on plate: $F_R = p_c A$
 Centroid: $y_c = \frac{(y_1 + y_2)}{2}$
 Pressure at Centroid:
 $p_c = \gamma y_c = \gamma (y_1 + y_2) / 2$
 Area: $A = bh$



Force on the plate: $F_R = b h \gamma (y_1 + y_2) / 2$
 Location of action (Method 1):
 $y_R = y_c + \frac{I_{xc}}{A y_c}$ with $I_{xc} = \frac{b h^3}{12}$, $A = b h$

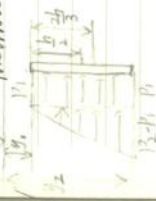
$$y_R = \frac{(y_1 + y_2)}{2} + \frac{\frac{b h^3}{12}}{b h \times \frac{(y_1 + y_2)}{2}} = \frac{(y_1 + y_2)}{2} + \frac{h^2}{6(y_1 + y_2)}$$

Method 2 for y_R :

decompose pressure prism into two;

part 1: rectangular, p_1 part 2: triangular, $p_2 - p_1$

Pressure Centers:

part 1: $y_{R1} = y_1 + h/2$ part 2: $y_{R2} = y_1 + 2h/3$ 

Wing moment balance

$$F_R y_R = F_1 y_{R1} + F_2 y_{R2}$$

where

$$F_1 = \gamma y_1 h b \quad \Rightarrow y_R$$

$$F_2 = \gamma h^2 b / 2$$

Exmp D: submerged by y_1 inclined wall, width b, length LForce on plate: $F_R = p_c A$ Centroid: $y_c = y_1 + (L \sin \theta) / 2$

Pressure at Centroid:

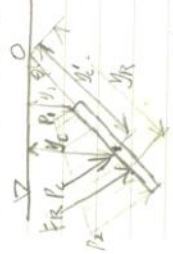
$$p_c = \gamma y_c = \gamma [y_1 + (L \sin \theta) / 2]$$

Area: $A = bL$ Force on the plate: $F_R = p_c A = bL \gamma [y_1 + (L \sin \theta) / 2]$

Pressure center (Method 1):

$$y_R = y_c + \frac{I_{xc}}{A y_c}, \text{ with } I_{xc} = \frac{1}{12} b L^3 \text{ and } A = bL$$

$$y_R = \frac{6 y_1^2 + 6 L y_1 \sin \theta + L^2 \sin^2 \theta}{3 \sin \theta (2 y_1 + L \sin \theta)}$$



4.2 Force on a curved surface

decompose force into F_v (vertical) and F_h (horizontal)• F_h : Force on projected vertical plane surface• F_v : Weight of liquid directly above(Real: $\downarrow$ Imaginary: $\uparrow$) F_v passes through the center of gravity of the liquid volume directly above the curved surface.• Resultant force: $F_R = \sqrt{(F_h)^2 + (F_v)^2}$